

# MULTIDIMENSIONAL DATA AGGREGATION AND VISUALIZATION FOR HUGE EXECUTION TRACE ANALYSIS

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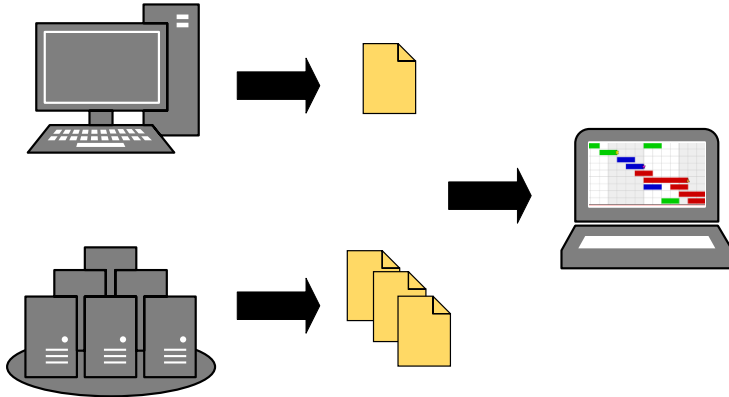


# TRACE VISUALIZATION PROBLEMATIC

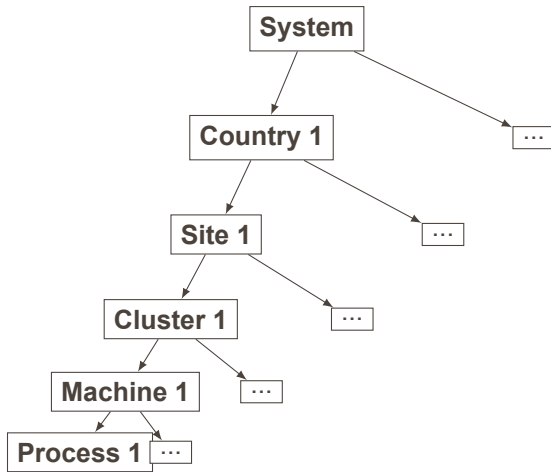
# PARALLEL AND DISTRIBUTED SYSTEM ANALYSIS



# TRACE-BASED ANALYSIS



# STRUCTURE: EXAMPLE OF HW/SW HIERARCHY



# TIMESTAMPED EVENTS THAT OCCUR DURING EXECUTION

## ► Punctual events

- Synchronization
- Flag
- Function call, return

## ► States

- Function (call → return)
- CPU state (idle, running)

## ► Variables

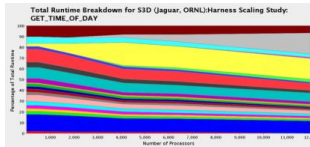
- CPU load
- Memory use
- HW/SW Counters

## ► Links

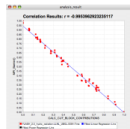
- Communication
- Context switch

# EXAMPLE OF CLASSIC ANALYSES

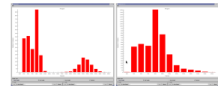
## Global Analysis



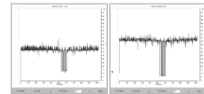
Execution Comparison



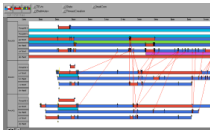
Correlations



Outliers

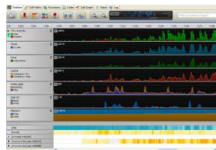


Workload



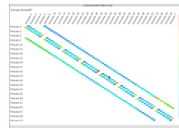
Causality relations

## Run behavior

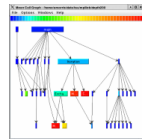


Resource usage

## Structure

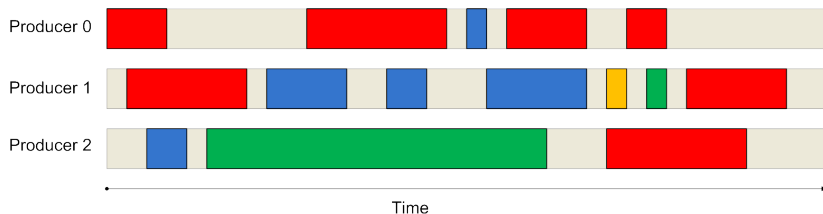


Communications



Call graphs

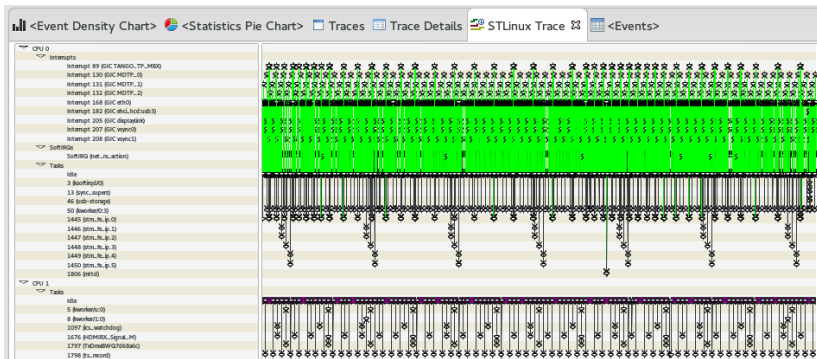
# SPACE-TIME REPRESENTATIONS PROBLEMATIC



- ▶ Structure can be composed of millions of resources
- ▶ Trace can contain billions of events (up to TB)



# LIMITED SCREEN SIZE ISSUES



# COMPUTATION - RENDERING - INTERACTIVITY ISSUES



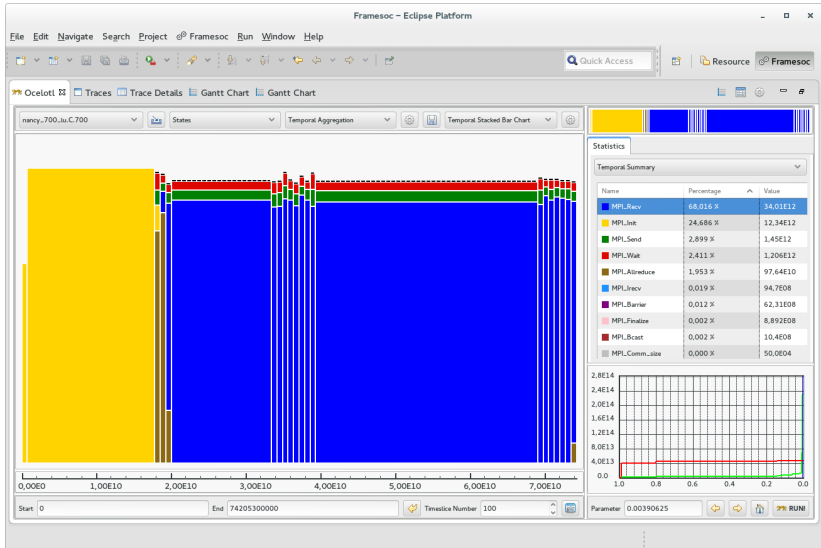
# ANALYST CAPABILITY LIMITS



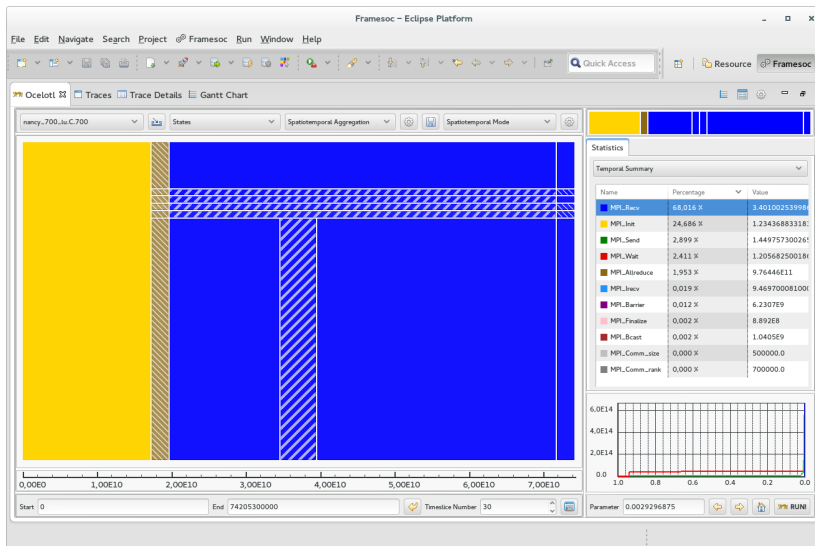
# OUR PROPOSAL: METHODOLOGY TO BUILD OVERVIEWS

- ▶ Overviews generated using **data and visual aggregation**
  - Temporal
  - Spatiotemporal
- ▶ Showing **meaningful information** (phases, perturbations)
- ▶ Enabling to adjust dynamically the **level of details**
- ▶ **Interaction:**
  - Zoom
  - Filtering
  - Synchronized statistics
  - Switch to other representations

# TEMPORAL ANALYSIS WITH OCELOTL TOOL

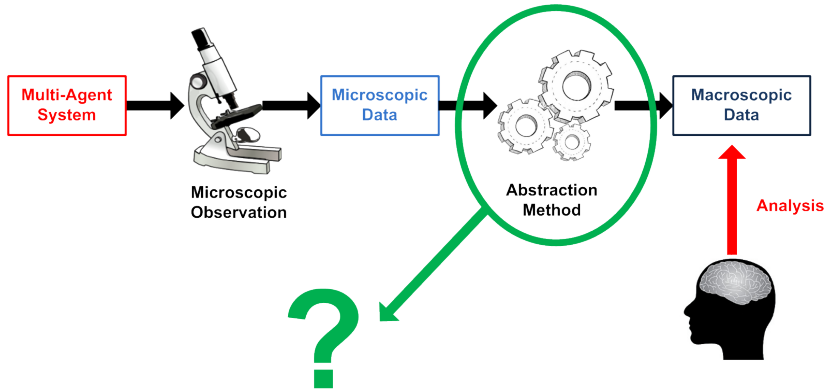


# SPATIOTEMPORAL ANALYSIS WITH OCELOT TOOL



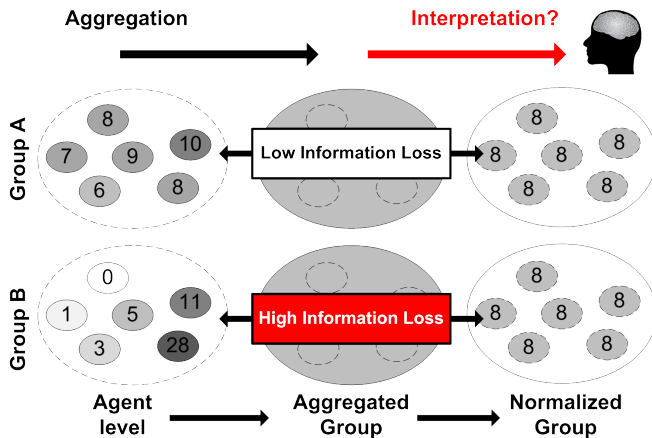
# DATA AGGREGATION METHODOLOGY

# ADAPTING AN AGGREGATION METHODOLOGY



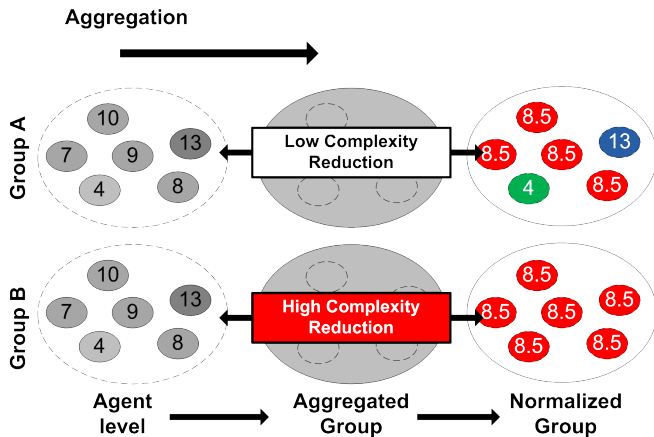


# INFORMATION LOSS: KL DIVERGENCE



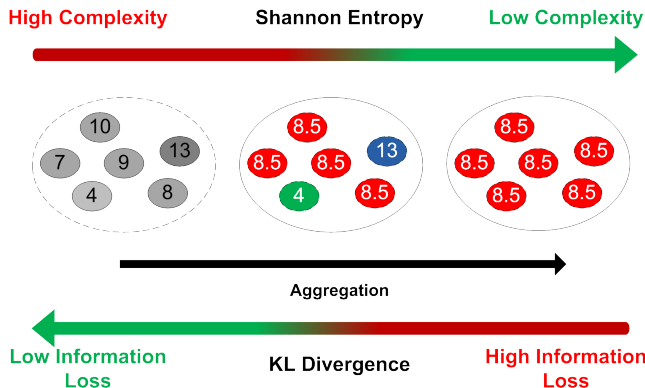
$$\text{loss}_E = \sum_{e \in E} \rho_e \log_2 \left( \frac{\rho_e}{\rho_E} \right)$$

# COMPLEXITY REDUCTION: SHANNON ENTROPY



$$\text{gain}_E = \rho_E \log_2 \rho_E - \sum_{e \in E} \rho_e \log_2 \rho_e$$

## TRADE-OFF: PIC



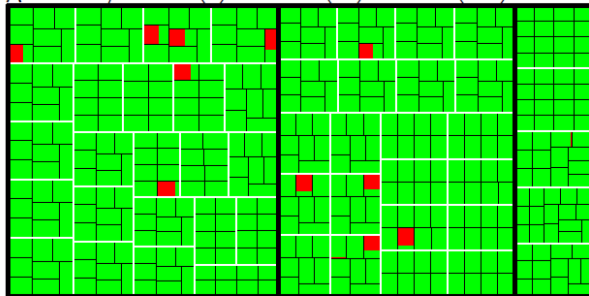
$$pIC_E = p \text{ gain}_E - (1-p) \text{ loss}_E$$

$$pIC_{\mathcal{P}} = \sum_{E \in \mathcal{P}} pIC_E$$

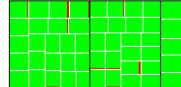
- For a given  $p$ : choose  $\mathcal{P}$  with the highest  $pIC$
- Aggregate in priority most homogeneous values

# VIVA: SPATIAL AGGREGATION (SCHNORR & LP)

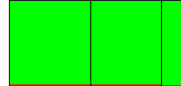
A Hierarchy: Cluster (3) - Machine (50) - Process (433)



A.1 Machine level



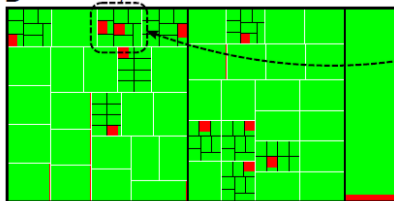
A.2 Cluster level



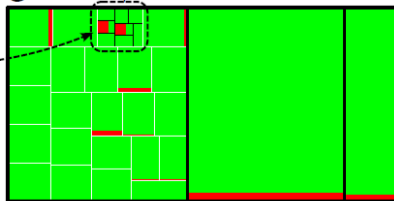
A.3 Full aggregation



B Ratio Gain/Loss with P = 10%

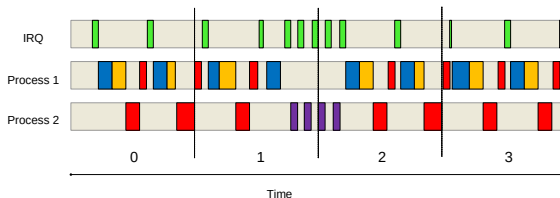


C Ratio Gain/Loss with P = 30%



# TEMPORAL OVERVIEW

# GENERATE A TRACE MICROSCOPIC MODEL

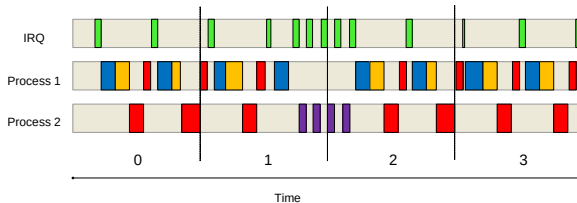


|           |     |     |     |   |
|-----------|-----|-----|-----|---|
| IRQ       | 0   | 0   | 0   | 0 |
| Process 1 | 1   | 2.1 | 1   | 3 |
| Process 2 | 4.1 | 2   | 4.1 | 4 |

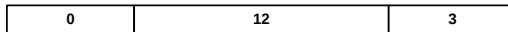
|           |   |     |   |     |
|-----------|---|-----|---|-----|
| IRQ       | 2 | 4.9 | 3 | 2.4 |
| Process 1 | 0 | 0   | 0 | 0   |
| Process 2 | 0 | 0   | 0 | 0   |

And so on...

# TEMPORAL AGGREGATION AND VISUALIZATION



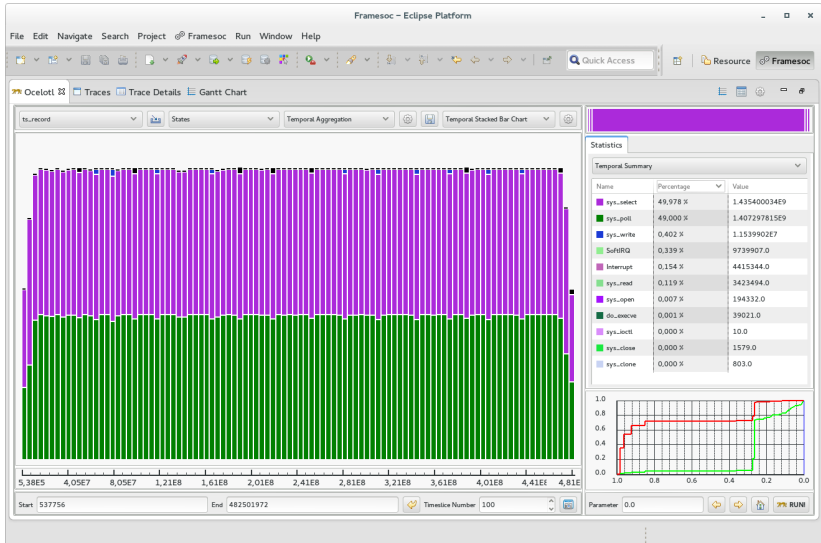
## Temporal Aggregation



## Spatial Aggregation

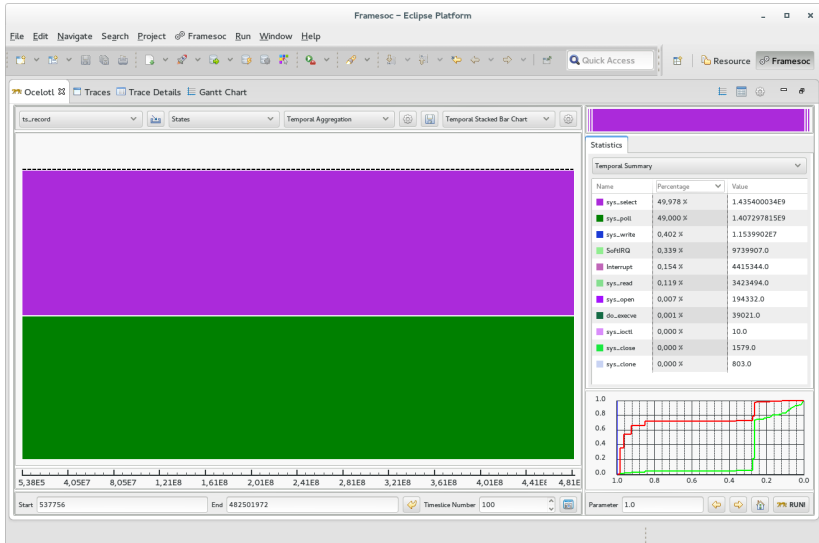


# MINIMUM INFORMATION LOSS: P=0

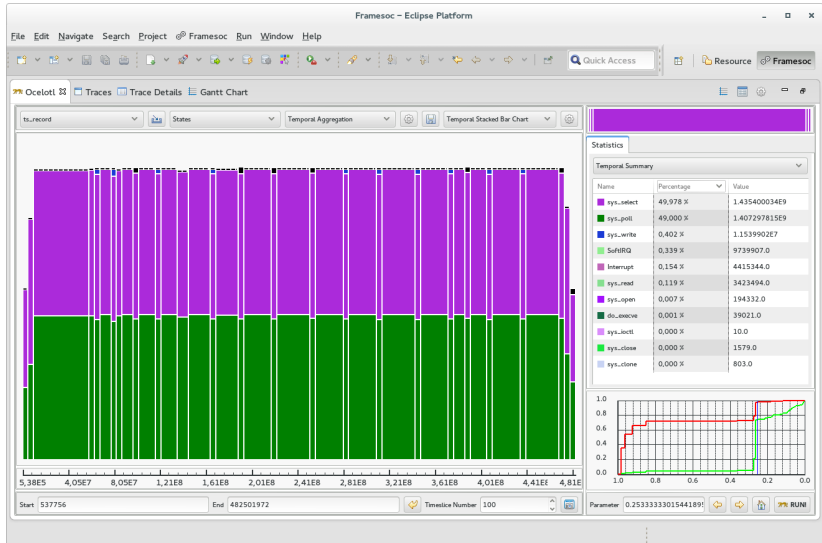




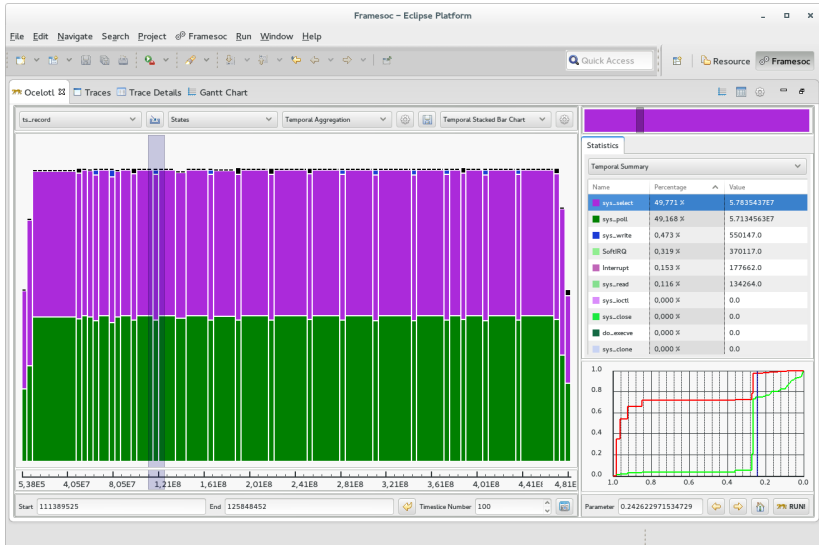
# MAXIMUM COMPLEXITY REDUCTION: P=1



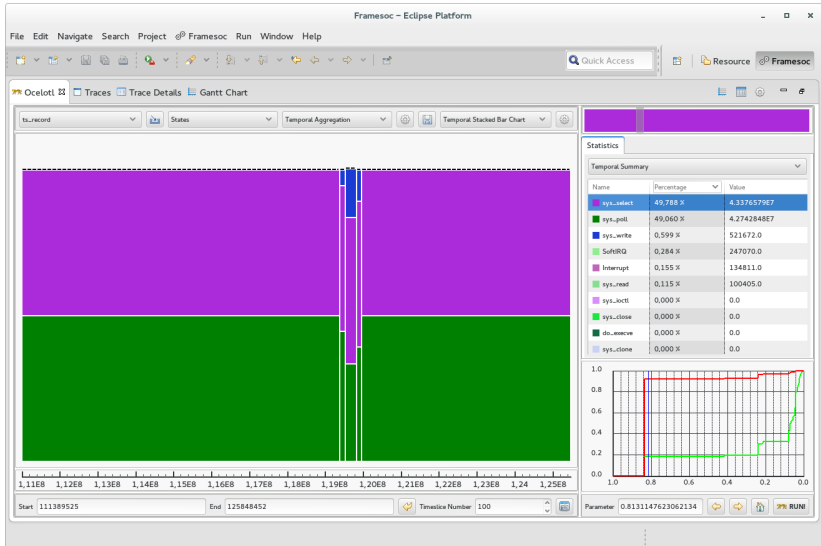
# INTERESTING TRADE-OFF



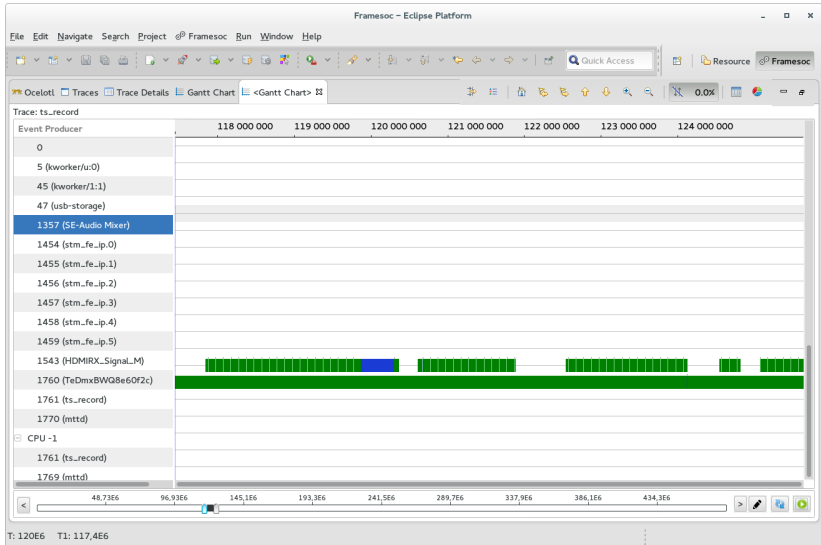
# SELECT A TEMPORAL AREA



## ZOOM

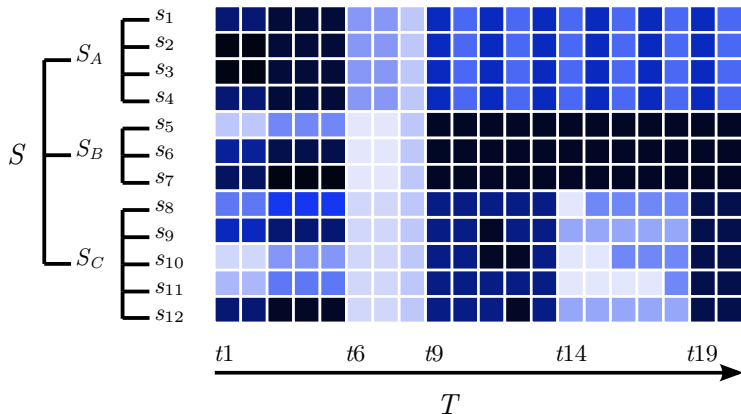


# MORE DETAILS WITH SPACE-TIME REPRESENTATION



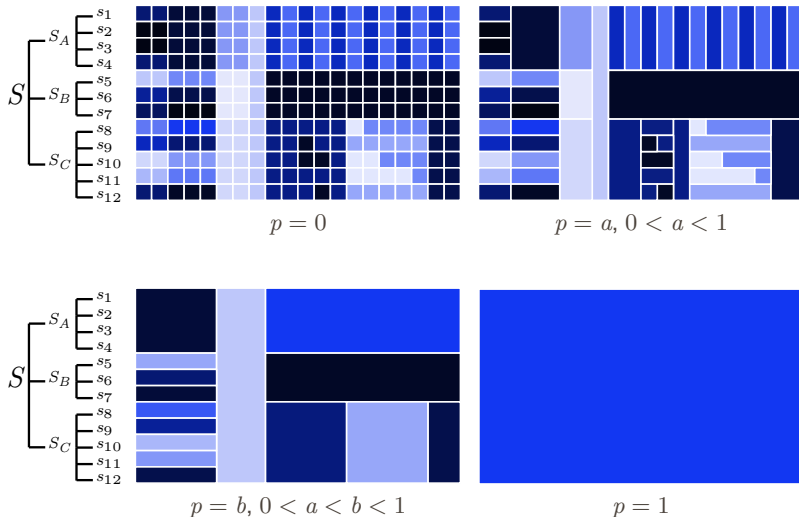
# SPATIOTEMPORAL OVERVIEW

## GENERATE A TRACE MICROSCOPIC MODEL



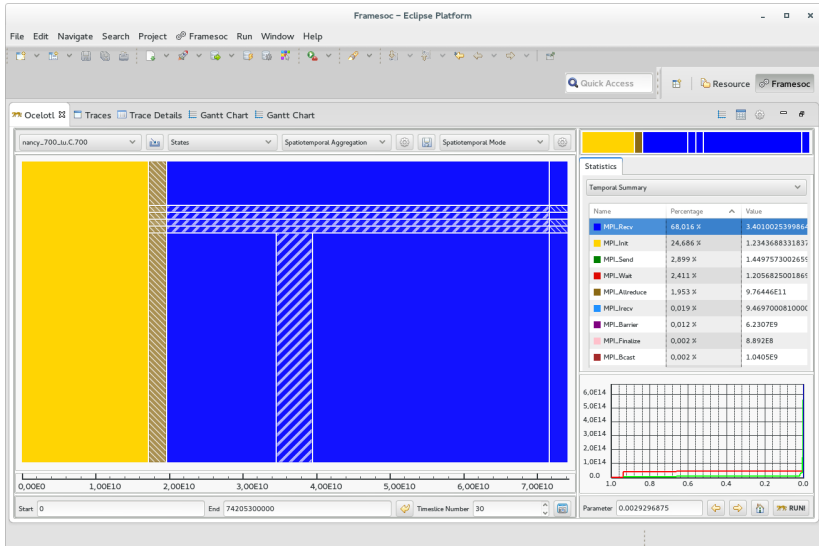
$$|X| = 2, \rho_x(s, t) = d_x(s, t)/d(t) \in [0, 1], \rho_1(s, t) = 1 - \rho_2(s, t)$$

## AGGREGATE THE MICROSCOPIC MODEL

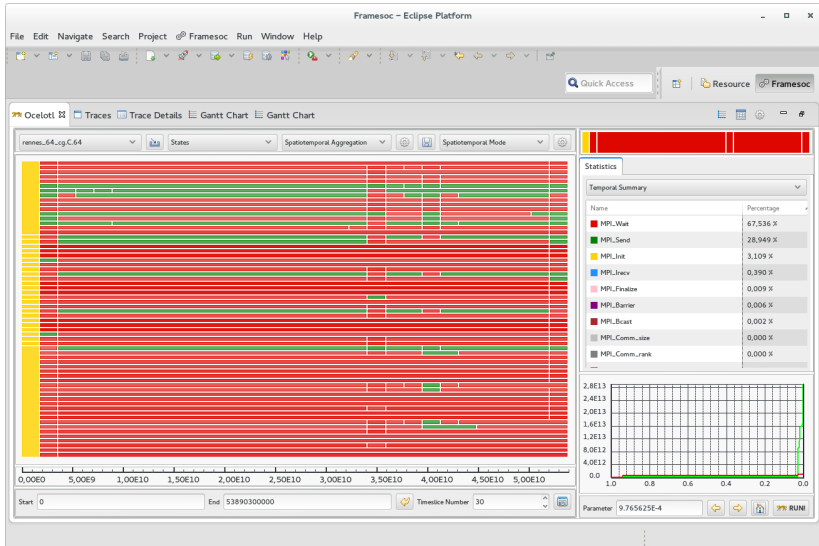




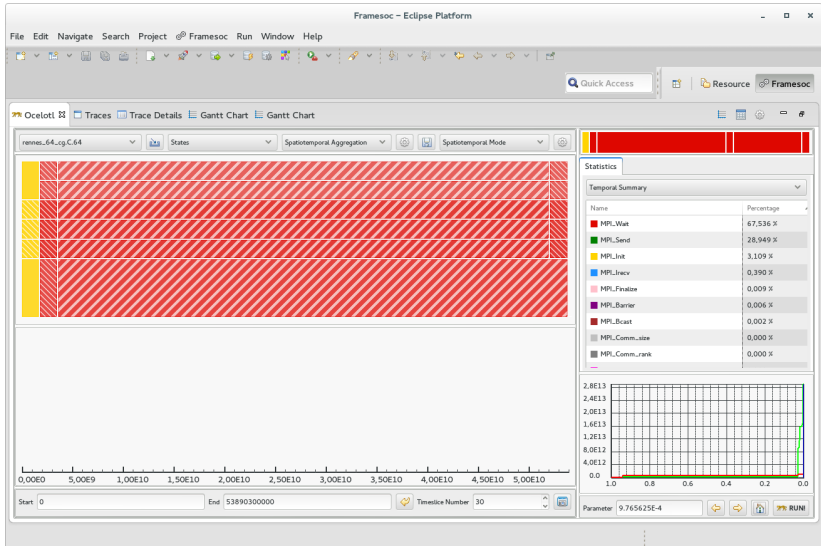
# INTERESTING TRADE-OFF



# NO VISUAL AGGREGATION



# VISUAL AGGREGATION



# CONCLUSION

# CONCLUSION

- ▶ **Visualizations based on data and visual aggregation**
  - Solves screen, computing and analyst capability **limitations**
  - Gives **meaningful information** about homogeneity (phases, perturbations)
- ▶ **Implementation:**
  - **Interaction** (zoom, switch to other tools)
  - **Performance** 5 min for a 12 GB trace (220 millions of events)
- ▶ **Globally:**
  - HPC tools mainly designed by the HPC community, to fit with its need
  - Collaboration with the InfoVis community would help to improve our visualization techniques
  - On the other side, our traces represent interesting use cases of huge quantities of data

# LINKS

**Ocelotl:**

<http://dosimont.github.io/ocelotl/>

# THANK YOU FOR YOUR ATTENTION



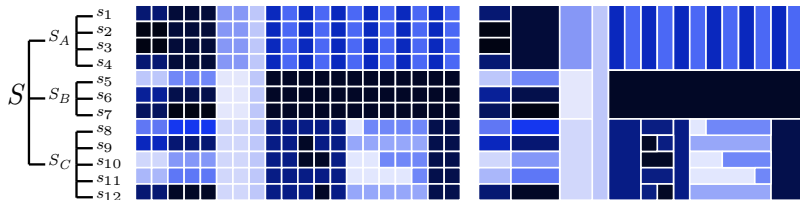
# DATA AGGREGATION METHODOLOGY

- ▶ A1. Choose a **model** and a **metric**
- ▶ A2. Choose on **which dimension(s)** aggregate
- ▶ A3. Define the **operands**
- ▶ A4. **Constrain** the aggregation :  $\rightarrow$  partitions  $\mathcal{P}$  allowed
- ▶ A5. Define the **operator**
- ▶ A6. Define the **trigger** - the aggregation condition
- ▶ A7. Build the **algorithm** satisfying A1-A6



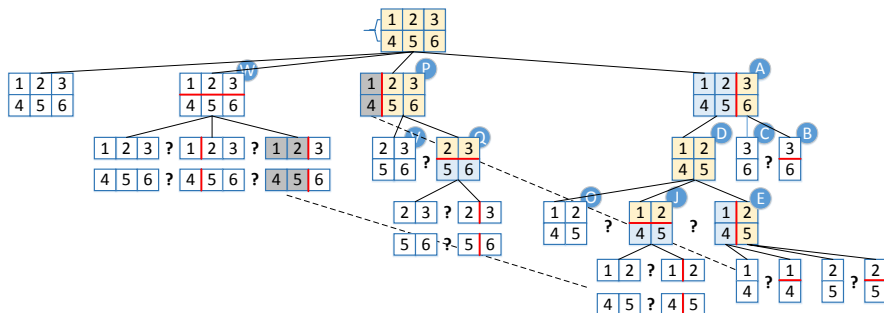
## A2-A5

- ▶ A2. We aggregate simultaneously on  $T$  and  $S$
- ▶ A3. Operands:  $(s, t) \in S \times T$
- ▶ A4. Constraint:  $\mathcal{A}(S \times T) = \mathcal{H}(S) \times \mathcal{I}(T)$   
Aggregation result is a partition  $\mathcal{P}(S \times T) \in \mathcal{A}(S \times T)$
- ▶ A5. Operator:  $+$
- ▶ A6. Trigger: maximize pIC of the partition  $\mathcal{P}(S \times T)$



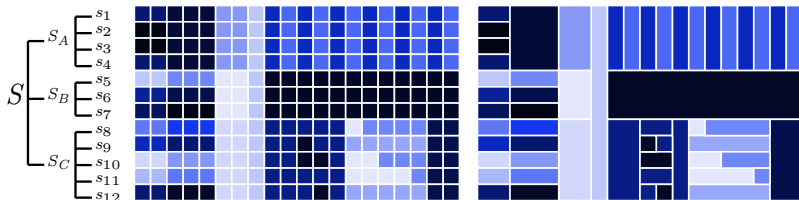
# BEST CUT ALGORITHM

- Compute the partition with the highest pIC :
  - Cut an area : time, space (or no cut)
  - Best cut: the partition  $\mathcal{P}$  where  $\sum_{E \in \mathcal{P}} \text{pIC}_E$  is max
  - Recursively cut and evaluate the partitions of  $E_1, E_2 \in \mathcal{P}$
  - Useless recomputation is avoided



## A6. TRIGGER THE AGGREGATION

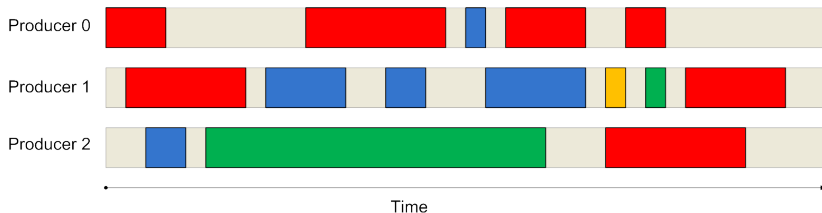
- ▶ Quantification of data reduction and information loss
  - aggregate the homogeneous areas
  - preserve the microscopic information of the heterogeneous areas
- ▶ Each  $(S_k, T_{(i,j)}) \in \mathcal{A}(S \times T)$  has an associated gain and loss
- ▶ gain and loss of a partition  $\mathcal{P}(S \times T)$  is the sum of gain and loss of its content  $(S_k, T_{(i,j)}) \in \mathcal{P}(S \times T)$



## ELMQVIST-FEKETE CRITERIA

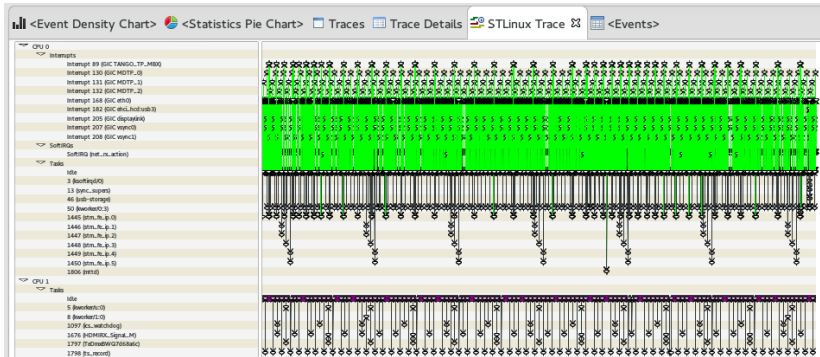
- ▶ **Shneiderman** : **overview**, zoom and filter, then get details on demand
- ▶ **Elmqvist & Fekete**: guidelines to design an **overview** visualization based on hierarchical aggregation
  - G1. Entity Budget
  - G2. Visual Summary
  - G3. Visual Simplicity
  - G4. *Discriminability*
  - G5. Fidelity
  - G6. *Interpretability*

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (1)



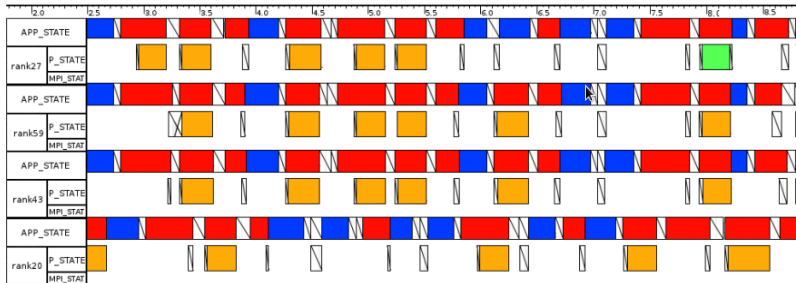
Example of Gantt chart - space-time diagram

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)



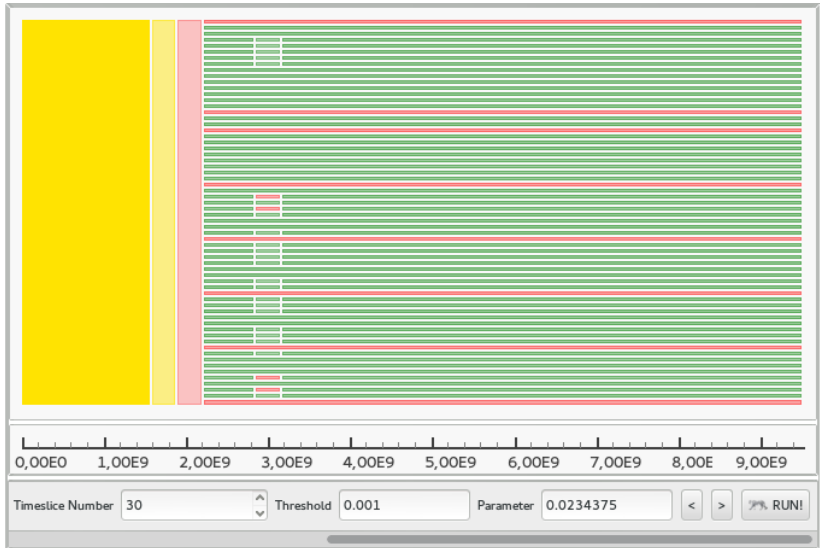
KPTrace:  $\overline{G1}$  (time),  $\overline{G2}$ ,  $\overline{G4}$ ,  $\overline{G5}$

# VISUALIZATIONS NOT FULFILLING THESE CRITERIA (2)



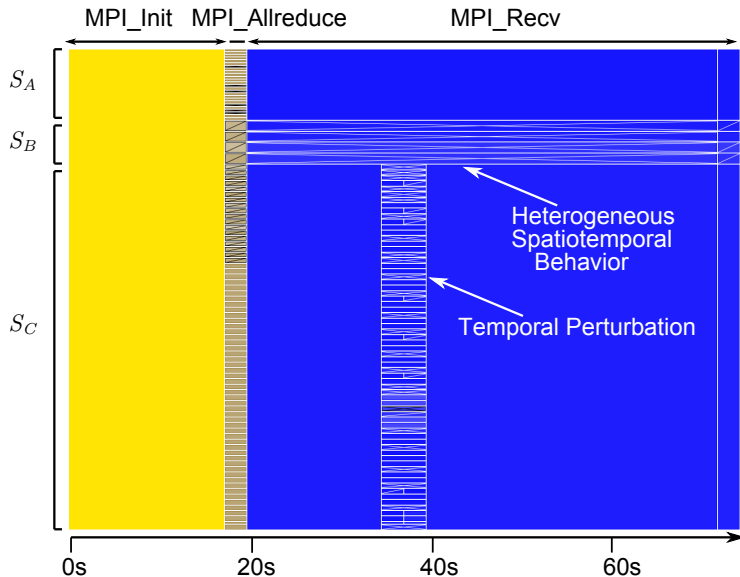
Pajé:  $\overline{G1}$  (space),  $\overline{G2}$

# CG CLASS C, 64 PROCESSES ON G5K RENNES





## LU CLASS C, 700 PROCESSES ON G5K NANCY



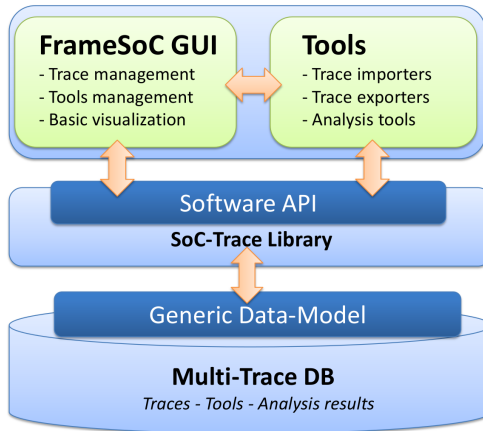
# PERFORMANCES (SPATIOTEMPORAL)

|                                                   | Case A      | Case B                                | Case C                                       | Case D                                          |
|---------------------------------------------------|-------------|---------------------------------------|----------------------------------------------|-------------------------------------------------|
| <b>Application</b>                                | CG, class C | CG, class C                           | LU, class C                                  | LU, class B                                     |
| <b>Processes</b>                                  | 64          | 512                                   | 700                                          | 900                                             |
| <b>Site</b>                                       | Rennes      | Grenoble                              | Nancy                                        | Rennes                                          |
| <b>Clusters (nodes)</b>                           | parapide(8) | adonis(9),<br>edel(24),<br>genepi(31) | graphene(26),<br>graphite(4),<br>griffon(67) | paradent(38),<br>parapide(21),<br>parapluie(18) |
| <b>Event number</b>                               | 3,838,144   | 49,149,440                            | 218,457,456                                  | 177,376,729                                     |
| <b>Trace size</b>                                 | 136.9 MB    | 1.8 GB                                | 8.3 GB                                       | 6.7 GB                                          |
| <b>Ocelotl computation times (30 time slices)</b> |             |                                       |                                              |                                                 |
| <b>Trace reading + Microscopic description</b>    | 5 s         | 31 s                                  | 222 s                                        | 174 s                                           |
| <b>Aggregation</b>                                | <1s         | <1s                                   | 2s                                           | 2s                                              |

# OCELOTL TOOL

- ▶ Implementation of the overview techniques
- ▶ Generic architecture. Add:
  - Your own **aggregation operator** (dimensions, metric)
  - Your own **visualization**
- ▶ Persistent caches to avoid long recomputations
- ▶ Integrated in **Framesoc**:
  - Trace and tools management
  - **Fast** trace reading (DB queries)
  - **Interaction** with other analysis tools
  - Also enable to **add you own tools**

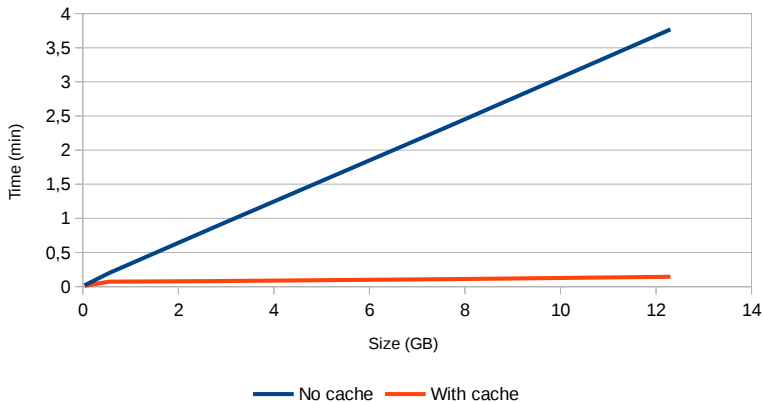
# FRAMESOC



- Trace format compatibility : Pajé (Akypuera: tool to convert from OTF2, Tau), LTTng, KPTrace

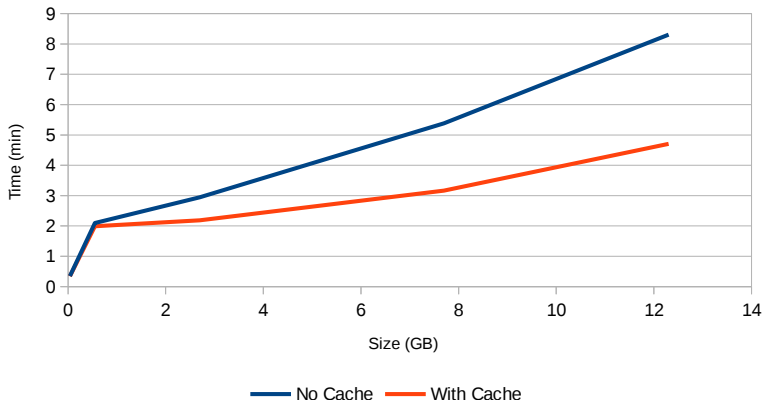
# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (100 time slices)



# PERFORMANCE: TEMPORAL ANALYSIS

Total analysis time as a function of trace size (1000 time slices)



# PERFORMANCE: SPATIOTEMPORAL ANALYSIS

Total analysis time as a function of trace size (30 time slices)

